

Lecture 28 Dynkin diagrams & root systems

Given a graph with no loops $\Gamma = (\Gamma_0, \Gamma_1)$ we'll construct a matrix

$A \in M_r(\mathbb{Z})$ that satisfies (\star) . Write $\Gamma_0 = \{1, \dots, r\}$,

$d_{ij} := |\{e \in \Gamma_1 \mid e \text{ connects } i \text{ and } j\}|$, and let $A_n = (a_{ij})$

with

$$a_{ij} := \begin{cases} -d_{ij}, & \text{if } i \neq j \\ 2, & \text{if } i = j \end{cases}$$

For example, for the Dynkin diagram A_4



we have

$$A_{\Gamma} = \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix}.$$

Given Γ as above, the set of roots of Γ is

$$\Phi_{\Gamma} := \{ v \in \mathbb{Z}^r \mid q_{\Gamma}(v) = 1 \},$$

where

$$q_{\Gamma}(v) = \frac{1}{2} v A_{\Gamma} v^t.$$

Let $\langle v, w \rangle_{\mathfrak{p}}$ be the symmetric bilinear form attached to $\mathfrak{g}_{\mathfrak{p}}$.

For each $j \in \Pi_0$ we define

$$\sigma_j: \mathbb{Z} \longrightarrow \mathbb{Z}$$

$$v \longmapsto v - \langle v, e_j \rangle_{\mathfrak{p}} e_j$$

Lemma Then $\forall j \in \Pi_0$

$$\sigma_j \mathfrak{I}_{\mathfrak{p}} \subseteq \mathfrak{I}_{\mathfrak{p}}.$$

Proof

We claim that σ_j preserves $\langle, \rangle_{\mathbb{R}}$. Indeed

$$\langle \sigma_j(v), \sigma_j(v) \rangle_{\mathbb{R}} = \langle v - \langle v, e_j \rangle_{\mathbb{R}} e_j, v - \langle v, e_j \rangle_{\mathbb{R}} e_j \rangle_{\mathbb{R}} =$$

$$\langle v, v \rangle_{\mathbb{R}} - 2 \underbrace{\langle v, e_j \rangle_{\mathbb{R}} \langle e_j, v \rangle_{\mathbb{R}}} + \underbrace{\langle v, e_j \rangle_{\mathbb{R}}^2 \langle e_j, e_j \rangle_{\mathbb{R}}}_{\substack{= \\ 2}} = \langle v, v \rangle_{\mathbb{R}},$$

Now note that

$$q_{\mathbb{R}}(\sigma_j(v)) = \frac{1}{2} \langle \sigma_j(v), \sigma_j(v) \rangle = \frac{1}{2} \langle v, v \rangle_{\mathbb{R}} = q_{\mathbb{R}}(v).$$

Thus $q_{\mathbb{R}}(v) = 1$ implies that $q_{\mathbb{R}}(\sigma_j(v)) = 1$ \square

Conversely, we shall attach to each root system Φ a graph Γ_Φ . First we pick a set of simple roots

$$\Delta = \{\alpha_1, \dots, \alpha_r\}$$

(i) $\forall i \in \{1, \dots, r\}$ draw a node.

(ii) $\forall i, j \in \{1, \dots, r\}$ draw $\langle \alpha_i, \alpha_j \rangle \langle \alpha_j, \alpha_i \rangle$ edges.

$\textcircled{1}$
 $\{0, 1, 2, 3\}$

We say that our root system Φ is reducible if

$\Phi = \Phi_1 \dot{\cup} \Phi_2$ with $(\Phi_1, \Phi_2) = 0$, and otherwise

we say that Φ is irreducible.

Thm If the root system Φ is irreducible then Γ_Φ is a Dynkin diagram.